

Network topology and protocols

18.1 Introduction

In 1969, the first major packet-switched communications network, the ARPANET, began operation. The network was originally conceived by the Advanced Research Projects Agency (ARPA) of the US Department of Defense for the interconnection of dissimilar computers, each with a specialised capability. Today systems range from small networks interconnecting microcomputers, hard-disks and laser-printers in a single room (e.g. Appletalk), through terminals and computers within a single building or campus (e.g. Ethernet), to large geographically distributed networks spanning the globe, e.g. the Internet. They are often classified as local, metropolitan or wide area networks (LANs, MANs or WANs). Figure 18.1 shows the relationships between LANs, MANs, WANs, the 'plain old telephone system' (POTS) and other more recent types of network. The major features of LANs, MANs and WANs are summarised in Table 18.1, after [Smythe 1991].

UK examples of WANs are the BT packet switched service (PSS) and the new joint academic network (SuperJANET). The original JANET interconnected all UK university

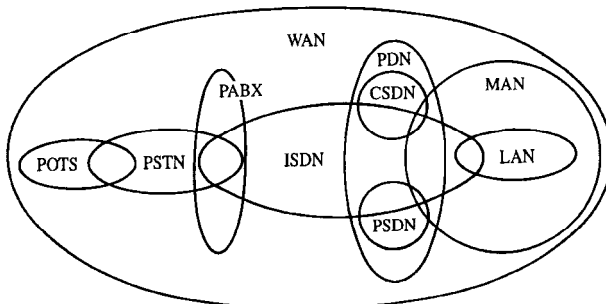


Figure 18.1 *Relationships between network architectures.*

LANs with a 5000 km backbone. With 100 Mbit/s transmission rates available on the individual university LANs the JANET backbone transmission rate has been progressively increased from 9.6 kbit/s to 2 Mbit/s. The main centres (London, Manchester, Edinburgh, etc.) were interconnected at 2 Mbit/s while other sites had 9.6 and 64 kbit/s access rates. The SuperJANET improvement upgraded the backbone bit rate to 34 and 140 Mbit/s using ATM (see section 19.7.2). Figure 18.2 shows the SuperJANET Phase B network, in which access rates are multiples of the 51.8 Mbit/s standard SDH interfaces (see section 19.4), within the PSTN core network. The equivalent US system is NSFnet which operates at 45 Mbit/s.

Table 18.1 *Comparison of LAN/MAN/WAN characteristics.*

| <i>Issue</i> | <i>WANs</i> | <i>MANs</i> | <i>LANs</i> |
|-----------------|---------------------|----------------|-----------------|
| Geographic size | 1000s km | 1 – 100 km | 0 – 5 km |
| No. of nodes | 10,000s | 1 – 500 | 1 – 200 |
| R_b | 0.1 – 100 kbit/s | 1 – 100 Mbit/s | 1 – 100s Mbit/s |
| P_b | $10^{-3} - 10^{-6}$ | $< 10^{-9}$ | $< 10^{-9}$ |
| Delays | > 0.5 s | 100 – 100s ms | 1 – 100 ms |
| Routing | sophisticated | simple | none |
| Linkages | gateways | bridges | bridges |

The general distinction between a LAN, MAN and WAN depends on the ratio of the network end-to-end propagation delay to the average packet duration. For a MAN this ratio is close to unity while the more closely coupled LAN has a ratio much smaller than unity. In the loosely coupled WAN, the ratio is much larger than unity [Smythe 1991].

Broadly speaking, networks can be divided into three main categories:

- **Circuit-switched:** in which a continuous physical link is established between the pair of communicating data terminal equipments (DTEs) for the entire duration of the communications session. Circuit switched networks most commonly utilise portions of the PSTN. Circuit switching is inefficient for variable bit rate transmission since the circuit must always support the highest data rate expected – hence the move towards packet switching and asynchronous transfer mode, ATM. (ATM is discussed in section 19.7.2.)
- **Message-switched:** in which the complete message (of any reasonable length) is stored and forwarded at each data network node. Physical connections between node pairs are made only for the duration of the message transfer between those node pairs and are broken as soon as the message transfer is complete. No complete physical path need therefore exist between communicating DTEs at any time.
- **Packet-switched:** in which each message is divided into many standard packets which are then routed individually through the network. Each packet is stored and forwarded at each network node. Messages are reassembled from their constituent packets at the receiving DTE. Two distinct varieties of packet switching exist: virtual circuit packet switching in which all packets follow the same route through the network, and datagram packet switching in which different packets (within the same



Figure 18.2 *SuperJANET wide area network (WAN).*

message) are routed entirely independently. Virtual circuit systems ensure that packets are received in their correct chronological order whilst datagram systems must include packet sequencing information for correct message reassembly.

Hybrids of, and variations on, the above switching philosophies are also sometimes used.

One of the major activities which accelerated the development of packet-switched technology to its present state was the development of the layered communications architecture concept. The proliferation of various architectures, creating possible barriers between different manufacturers' systems, led the International Standards Organisation (ISO) to launch the reference model for Open Systems Interconnection (OSI). This standardised the systems interfaces.

18.2 Network topologies and examples

Any network [Hoiki] must fundamentally be based on some interconnection topology, to link its constituent terminals. The main network topologies are reviewed here.

18.2.1 Point-to-point

This is undoubtedly the simplest wired network type, and is extensively used. It may be transitory and exist only for the duration of the call, as on the circuit-switched PSTN, or may exist permanently, as on a private (leased) line. This configuration is commonly used when a limited number of physically distinct routes are required.

18.2.2 Multidrop

When a large number of locations, which can be partitioned into geographical clusters, are required to be connected a multidrop or bus configuration is often employed, Figure 18.3, where the terminals are connected via taps. All transmissions from node A can be received by nodes B, C and D. However, only one of the latter nodes may transmit at any one time over the network, to avoid contention, as there is only one data transmission path. This constraint is enforced by employing a polling protocol at A which addresses B, C and D in turn, permitting only the addressed node to reply.

Multidrop connection provides a way of reducing transmission link costs by utilising a single branched circuit to connect A to B, C and D. The principal current application of this topology is the connection of host computers to terminals – or terminal clusters – at several locations. Multidrop is really only an alternative description of the later bus system of Figure 18.8. Multidrop connection is under consideration for optical fibre replacement of the PSTN local loop copper connection (section 19.7.3) with a passive optical network (PON).

18.2.3 Star

Centralised switched-star network configurations have now existed for over a century in the PSTN and, for this reason, represent perhaps the best understood class of network. In the star configuration, the devices comprising the network are connected by point-to-point links, to a central node or computer, Figure 18.4. The star network has two major limitations:

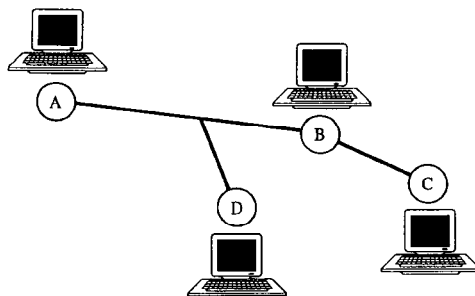


Figure 18.3 Multidrop network concept.

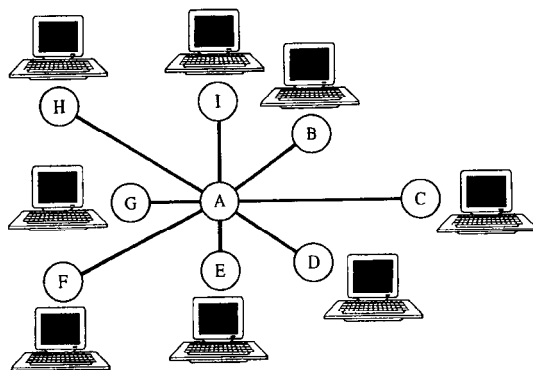


Figure 18.4 *Basic star network.*

- The remote devices are unable to communicate directly and must do so via the central node, which is required to switch these transmissions as well as carrying out its primary processing function.
- Such a network is very vulnerable to failure, either of the central node, causing a complete suspension of operation, or of a transmission link. Therefore, reliability and/or redundancy are particularly important considerations for this topology.

Despite these limitations, the star configuration is important as it has been used extensively for telephone exchange connections and in fibre optic systems. (Until recently it has been difficult to realise cheap, passive, optical couplers for implementation of an optical fibre ring or bus system, hence the attraction of the star network.) This topology is also used for many VSAT networks, section 14.3.9.

18.2.4 Ring

This network consists of a number of devices connected together to form a ring, Figure 18.5. Ring networks employ broadcast transmission, in that messages are passed around the ring from device to device. Each device receives each message, regenerates it, and retransmits it to its neighbour. The message is only retained, however, by the device to which it was addressed. Two variations of the ring network exist. These are:

- Unidirectional: in which messages are passed between the nodes in one direction only. The host, A, controls communication using a mechanism known as 'list polling'. The failure of a single data link will then halt all transmissions.
- Bidirectional: in which the ring is capable of supporting transmission in both directions. In the event of a single data link failing, the host, A, can then maintain contact with the two sectors of the network.

That each network node is involved in the transmission of all data on the network is a potential weakness. The ring topology is simple both in concept and implementation, however, and is popular for fibre optic LANs in which regenerative repeaters are required

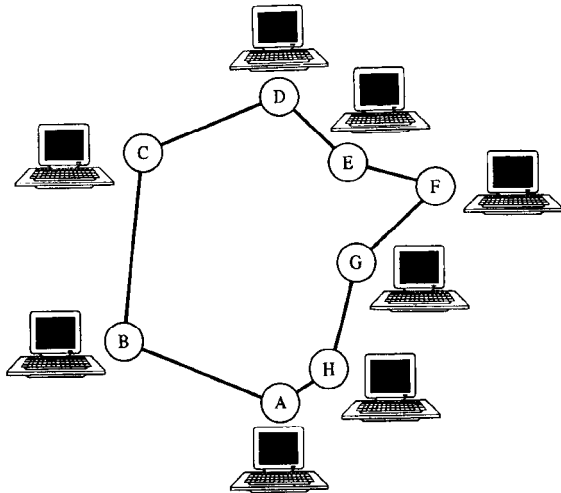


Figure 18.5 Ring network.

at each node. Access is via slots or tokens. A simple token ring operates essentially as follows.

A token bit pattern (e.g. 11111111), which is prevented from appearing in genuine data using a technique called bit stuffing, circulates while the ring is idle. A terminal 'captures' the token by removing it, or altering it (e.g. to 11111110). The terminal 'possessing' the token can then transmit one or more packets around the ring, each node in the ring acting as a repeater. Each transmitted packet contains a destination address in its header which is recognised by the destination terminal. The destination node reads the data and signifies receipt by setting response (or acknowledgement) bits in the packet trailer. It then retransmits the packet. When the sending terminal receives the packet with the response bits correctly set it resets the token to the idle pattern and recirculates it around the ring.

Cambridge ring

The Cambridge ring employs the empty slot principle. A constant number of fixed-length data packets – slots – circulate continuously around the ring in one direction only, a full/empty indicator within the slot header being used to signal the state of the slot. To transmit a node occupies the first empty slot by setting the full/empty flag to full and placing its message in the slot. The data packet then completes one revolution of the ring before the sending node 'empties' the slot and resets the indicator to empty. (A minor variation is to allow the receiver to empty the slot.)

The CR82 Cambridge ring, Figure 18.6, is a baseband implementation of a slotted ring using twisted wire pair cable, a bit rate of 10 Mbit/s and, typically, 10 slots. A monitor station checks which stations are active, and fills dummy slots to confirm that the

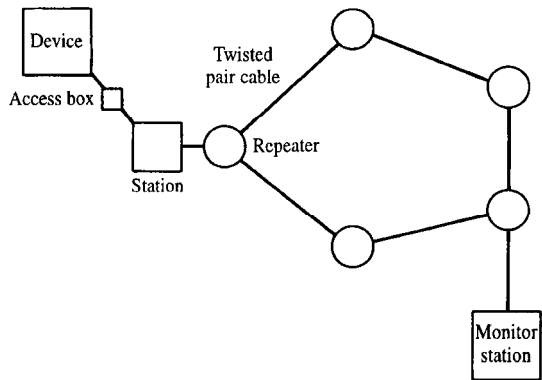


Figure 18.6 *Cambridge backbone ring example.*

ring is unbroken. With optical fibre implementations the data rate can be increased to 600 Mbit/s and beyond.

18.2.5 Mesh

While the star configuration is best suited for host computer/slave terminal connections on a one-to-many basis, mesh networks, Figure 18.7, are primarily used in a many-to-many situation, such as typically exists in WANs. Fully interconnected mesh networks, for more than a small number of nodes, are generally expensive as they require a total of $\frac{1}{2}n(n - 1)$ links for n nodes. They are very resilient to failure, however, since alternative routes are available if a link fails. Where link lengths are long or data volumes low, a public packet-switched service may offer a significant cost advantage over a private mesh network. Unlike the ring or star topologies, adding a node to an existing (n node) mesh

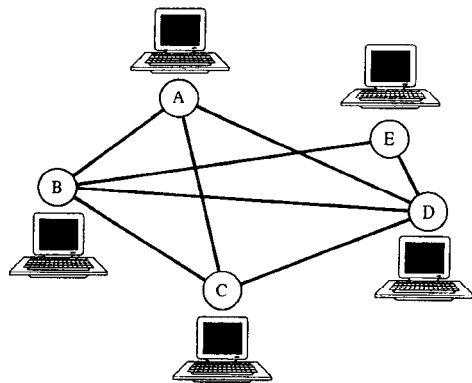


Figure 18.7 *Mesh network.*

network necessitates a further $n - 1$ new connections.

18.2.6 Bus

Bus networks employ a broadcast philosophy. The bus is formed from a length of cable to which devices are attached by cable interfaces, or taps, Figure 18.8. Messages from a device are transmitted (bidirectionally) to all devices on the bus simultaneously; however, devices accept only those messages addressed to themselves. Since devices are not required to retransmit the messages, there is none of the delay (latency) or complexity associated with the ring topology.

The bus configuration is extremely tolerant of terminal failures, since operation of the network will usually continue if one of the active-component devices fails. A further advantage is that bus networks are easily reconfigured and extended. The bus topology is often expanded to form a tree structure, especially appropriate for use in multistorey buildings. (Another broadcast technique, similar in concept to a physical bus, is that traditionally used by satellite linked networks.) Access to the bus transmission medium is discussed in section 18.5. The small computer system interface (SCSI) is a dedicated bus used to connect discs and tape drives directly to the processor of a computer system.

Ethernet bus

Ethernet [Hoiki] is an example of a proprietary bus network, Figure 18.9(a). In this implementation a simple passive medium and transparent high impedance taps are employed. Of particular importance are the (coaxial cable) line terminators, which serve as matched loads to ensure reflections do not corrupt data transmission. Typical data rates are 1 Mbit/s and 10 Mbit/s, with a maximum bus length of 500 m. Figure 18.9(b) shows, for a 10 Mbit/s system, the expected number of attempts required to access the bus for different levels of network load. Ethernet uses 32-bit polynomial codes (section 10.8.1) for error detection.

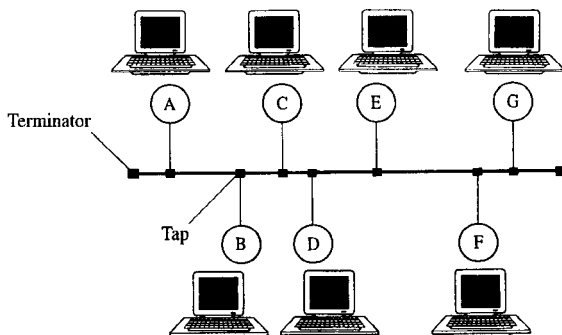


Figure 18.8 *Bus network.*

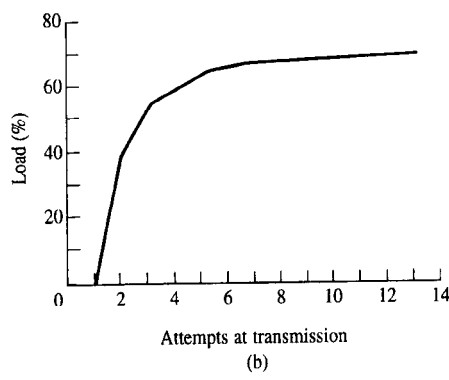
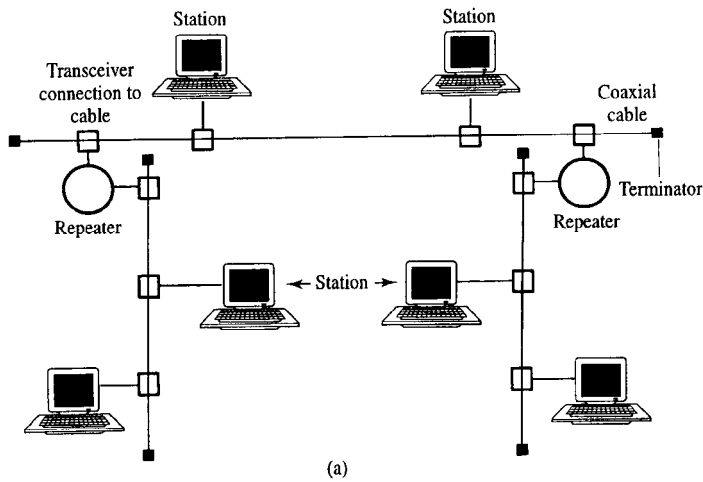


Figure 18.9 *Ethernet: (a) example configuration; (b) typical system response showing how the number of attempts at transmission varies with network load.*

18.2.7 Transmission media

Networks can utilise wire, coaxial cable, fibre optic or wireless links. Table 18.2 compares the different cabled and wireless transmission media. Metallic cable is preferred for many systems as simple, passive, tapped junctions cannot easily be realised for optical fibres. In all systems propagation loss, distortion, delay and noise are potential impairment mechanisms. Many systems use coaxial cable operating with baseband pulse rates up to 10 Mbit/s over 500 m paths. At higher rates ‘broadband’ data is modulated onto an RF carrier of, typically, 100 MHz, or fibre optic transmission (section 19.5) is used. Recently short runs of simple twisted wire pair have also become attractive for broadband transmission, because optical fibres are 5 to 10 times more expensive than twisted pair cable installations. In the near future broadband wireless LAN technology

using carrier frequencies of 5 GHz and 17 GHz will become important.

Table 18.2 Typical cost per node, data rate and ranges for different transmission media.

| Transmission medium | Twisted pair | Coaxial | Fibre optic | Radio | Infra-red |
|-----------------------|--------------|--------------|-------------|-------------|-----------|
| Range, m | 1 – 1,000 | 10 – 10,000 | 10 – 10,000 | 50 – 10,000 | 0.5 – 30 |
| Data rate, kbit/s | 0.3 – 2,000 | 300 – 10,000 | 1 – 100,000 | 1 – 10 | 0.05 – 20 |
| Cost/node, US dollars | 10 – 30 | 30 – 50 | 75 – 200 | 50 – 100 | 20 – 75 |

18.3 Network coverage and access

The first computer WAN, ARPANET, spanned the US and was later extended to Europe. With the rise in the number of potential digital communications users, many of the bodies responsible for post, telegraph and telephone (PTT) services have now built such networks. These WANs generally use store and forward systems in which messages are held in a node store before being switched, via an appropriate transmission link, to another node nearer the message's ultimate destination. With 10 to 50 kbit/s data rates the end-to-end delay is of the order of seconds. WANs can be classified as follows:

- **Public networks:** For example, the British Telecom Gold electronic mail service, the international EUNET (a packet switched service (PSS), which exists primarily for accessing information databases) and the Internet.
- **Private networks:** For many users, public data networks do not provide the services required. Private telecommunications networks leased on a semi-permanent basis, such as SWIFT employed by the banking fraternity, are one alternative.
- **Value added networks:** A value added network (VAN) uses conventional PTT facilities combined with specialised message-processing services to add value to the network. The user is offered flexibility and the economies of shared usage. Examples include TRANSPAC and the specialised banking EFTPOS networks.

Local area networks (LANs) are specifically designed for the interconnection of computer systems and peripherals within a geographically small site, such as a single building or university campus, and are generally privately owned. A LAN has many of the features of a WAN, but it also has its own, distinct, characteristics, i.e.:

- Wide bandwidth, of the order of tens of Mbit/s.
- Low (1 to 10 μ s) delay due to resource sharing, and absence of buffering.
- Low probabilities of bit error, typically 10^{-9} to 10^{-11} .
- Simple protocols (compared with those necessary for the longer ranges of WANs).
- Low cost and easy installation.
- High degree of connectability and compatibility of physical connections.
- Geographically bounded, with a maximum range of approximately 5 km.

Metropolitan networks or MANs which may be up to 50 km in diameter lie between LANs and WANs. An access method (or protocol) defines the set of procedures for LAN access to a WAN and vice versa. Since LAN transmission rates are much higher than

those of interconnecting WANs one LAN network node must normally be dedicated to the WAN interface. With high speed MAN interconnection of LANs it is possible to transfer large files electronically, rather than physically using, for example, discs, tapes or CD-ROMs. Two of the most common network interconnection techniques utilise bridges and gateways.

18.3.1 Bridges and gateways

A bridge is a device that interconnects two networks of the same type (using the same protocol). The bridge utilises a store and forward feature to receive, regenerate and retransmit packets while filtering the addresses between connected segments. A gateway on the other hand [Smythe 1995] connects networks using different protocols, typically LANs and WANs. They can therefore provide transparent access to resources on other, remote, networks. It is a similar device to the bridge but also performs the necessary protocol conversion. The JANET network of Figure 18.2 has transparent gateway connections to other X.25 international networks, which link it to the Internet, section 18.7.6.

18.3.2 Network switches

With the increasing power of VLSI technology, a large switch array can now be implemented on a single chip. National Semiconductor developed a 16×16 switching matrix in $2 \mu\text{m}$ CMOS gate array technology in the late 1980s. Figure 18.10 shows an 8×8 *Banyan* switch, consisting of twelve 2×2 switching elements. There is only one route through the switch from each input to each output. At each stage in this switch the upper or lower output is chosen depending on whether a specific digit in the route control overhead is 1 or 0. This is one of the simplest switch arrays that can be constructed and illustrates the self-routing capability of a packet navigating a network composed of such switches. When routing and sorting is performed locally at each switch in a network

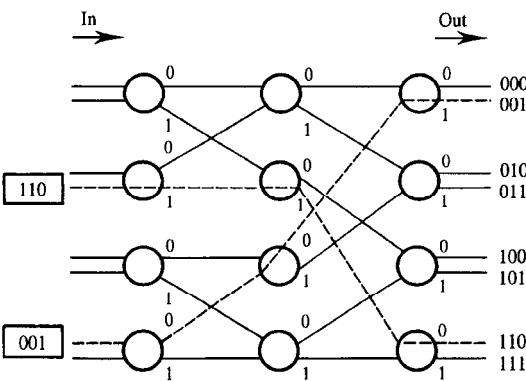


Figure 18.10 8×8 *Banyan* packet switching network.

there is no need for recourse to a centrally located processing centre and the throughput is therefore greater than that of a circuit switched network. Dashed lines in Figure 18.10 show two example paths that packets with specific route headers would take through the network.

A problem inherent in all packet switched networks is that of packet collision or blocking (i.e. packets arriving simultaneously on the two inputs of a single switching element). To reduce packet collisions, the network can be operated at higher speed than the inputs or storage buffers can be introduced at the switch sites.

To remove packet collisions completely, the input packets must be sorted in such a way that their paths never cross. The technique normally used to perform this operation is known as Batcher sorting, in which the incoming packets are arranged in ascending or descending order according to route header. (Another non-blocking technique is the crossbar switch which was used in the 1970s for PSTN design.)

The Starlight network switch, which uses both Batcher sorting and Banyan switching, is shown in Figure 18.11. A CMOS 32×32 Batcher–Banyan switch chip in the early 1990s operated at 210 Mbit/s. Batcher–Banyan switching is not able to resolve the problem of output blocking, when multiple packets are destined for the same output port, but this can be overcome by the insertion of a trap network between the sorting and switching networks, Figure 18.11. The loss of trapped packets is overcome by recirculating the duplicate address packets into the next sorting cycle to eliminate the need for buffered switch elements.

The network is packet synchronous if it requires all packets to enter the network at the same time. Banyan networks can be operated packet asynchronously because each packet's path through the self-routing network is, at least to first order, unaffected by the presence of other packets. Packet switches such as these, which can operate at input rates of up to 150 Mbit/s, have been realised. (Note that the Banyan name is now often associated with a particular commercial system.)

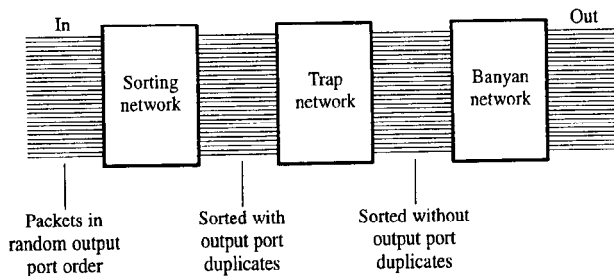


Figure 18.11 Starlight packet sorting-switching network.

18.4 Reference model for terminal interfacing

Most network architectures are organised as a series of layers. Previously the number, name and function of each layer differed from network to network. In all cases, however, the purpose of each layer was, and is, to offer certain services to higher layers, while shielding the details of exactly how those services are implemented in the lower layers.

Layer n at one node holds a conversation with layer n at another node. The rules and conventions used in this conversation are collectively known as the layer n protocol. The main functions of such a protocol are:

- Link initiation and termination.
- Synchronisation of data unit boundaries.
- Link control, with reference to polling, contention restriction and/or resolution, time-out, deadlock and restart.
- Error detection and correction.

The messages or blocks of data passed between entities in adjacent layers (i.e. across interfaces) are known as data units. With the exception of layer 1 no data is directly transferred from layer n at one node to layer n at another. Data and control information is passed by each layer to the layer immediately below, until the lowest layer is reached. It is only here that there is physical communication between nodes. The interfaces between layers must be clearly defined so that:

- The amount of data exchanged between adjacent layers is minimised.
- Replacing the implementation of a layer (and possibly its subordinate layers) with an alternative (which provides exactly the same set of services to its upstairs neighbour) is easily achieved.

18.4.1 The ISO model

This is a set of layers and protocols used to model network architecture, Figure 18.12. The overall purpose of the International Standards Organisation (ISO) model is to define standard procedures for the interconnection of network systems, i.e. to achieve open systems interconnection (OSI). ISO OSI processing is normally performed in software but, with the continuous rise in data rates, hardware protocol processors are, increasingly, being deployed. Several major principles were observed in the design of the ISO OSI model. These principles are that:

- A new layer should be created whenever a different level of abstraction is required.
- Each layer should perform a well defined service related to existing protocol standards.
- The layer boundaries should minimise information flow across layer interfaces.
- The number of layers should be sufficient so that distinct functions are not combined in the same layer, but remain small enough to give a compact architecture.

This has resulted in agreement to use seven layers as the OSI standard. The layers of the model are presented from the viewpoint of connection-mode transmission, starting from the interface to the physical medium. A key feature of the ISO OSI model is that it

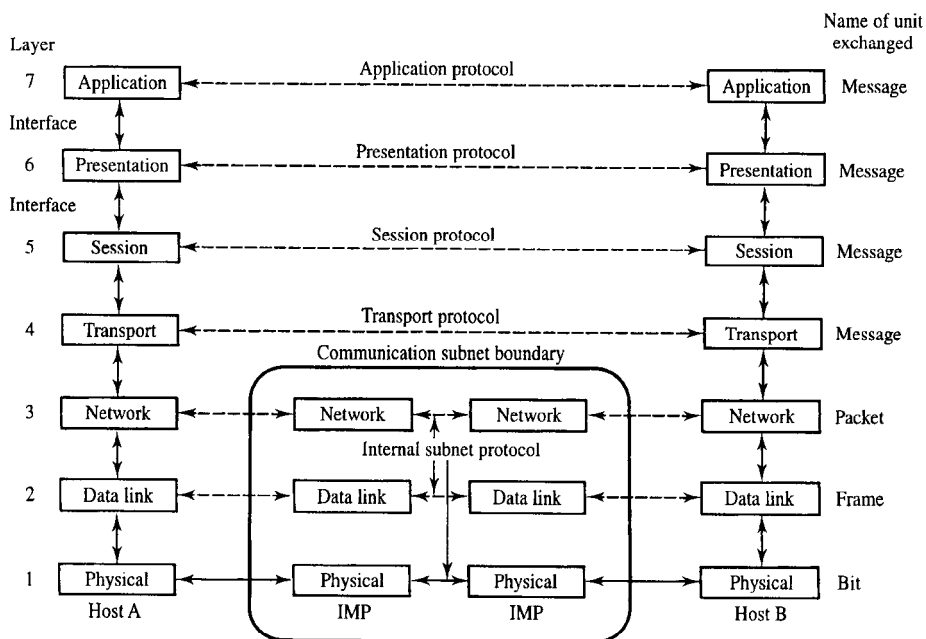


Figure 18.12 ISO OSI reference model.

achieves standardisation for data communications combined with error free transmission. A summary of function distribution is provided in Figure 18.12. The physical layer (1) directly interfaces with the transmission medium. This layer therefore includes: mechanical aspects, e.g. specification of cables and connectors; electrical aspects, e.g. specification of voltage levels, current levels and modulation techniques; functions and procedural aspects for the interface to the physical circuit connection.

The task of the data link layer (2) is to take the raw transmission facility and transform it into a link that appears free of transmission errors. It accomplishes this task by breaking the input data into data frames, transmitting the frames sequentially, and processing acknowledgement frames returned by the receiver. This is illustrated in Figure 18.13. Here once the packet is transmitted the transmitter stops and waits for an acknowledgement before the next packet is sent. If the acknowledgement does not arrive from the remote terminal within a prescribed time interval then the original packet is retransmitted, as shown in Figure 18.13 for packet 2.

The data link layer must both create and recognise frame boundaries. It thus defines the protocols for access to the network. Cyclic redundancy or polynomial codes (Chapter 10) are widely used in the data link layer to achieve an error detection capability on the bit-serial data. These processing functions are implemented in hardware. Software packages, such as Kermit, are located here to provide terminal emulation and file transfer facilities. The first two layers together are sometimes called the hardware layer.

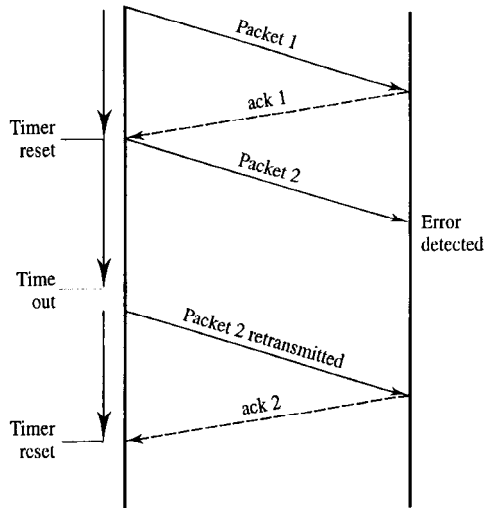


Figure 18.13 *Protocol for acknowledging (ack) successful packet receipt.*

The purpose of the network layer (3) is to provide an end-to-end communications circuit. It has responsibility for tasks such as routing, switching, and interconnection, including the use of multiple transmission resources, to provide a virtual circuit. The bottom three layers, collectively, implement the network function – and can be envisaged as a ‘transparent pipe’ to the physical medium, Figure 18.12. Data routed between networks, or from node to node within a network, require these functions alone.

The next layer (4) provides a transport service, suitable for the particular terminal equipment, that is independent of the network and the type of service. This includes multiplexing independent message streams over a single connection and segmenting data into appropriately sized units for efficient handling by the lower layers. Modulo $2^n - 1$ checksums (Chapter 10) are frequently computed within the software communications protocols of this layer, and compared with the received value, to determine whether data corruption has occurred. The transport layer can implement up to five different levels of error correction, but in LANs little error correction is required.

The functions of the session layer (5) are to negotiate, initiate, maintain and terminate sessions between application processes. This could for example be a transaction at a bank cash card machine. The layer operates in either half or full duplex, section 15.1.1.

While the session layer (5) selects the type of service, the network layer (3) chooses appropriate facilities, and the data link layer (2) formats the messages. The presentation layer (6) ensures that information is delivered in a form that the receiving system can interpret, understand and use. For example it defines the standard format for date and time information. The services provided by this layer include classification, compression and encryption of the data using codes and ciphers and also conversion, where necessary, of text between different types, e.g. to and from ASCII. The overall aim of layer 6 is to

make communication machine independent.

The application layer (7) defines the network applications that support file serving. Hence it provides resource management for file transfer, virtual file and virtual terminal emulation, distributed processing and other functions. Conceptually this is where X.400 electronic mail [Wilkinson] and other network utility software resides. In electronic mail applications, layer 7 contains the memories which store the messages for forwarding when network capacity becomes available.

These ISO layers are equivalent to similar functions in other layered communications systems and hence there is commonality between OSI and other standards which have OSI equivalence. As one moves down the layers overhead bits (added by each layer) come to dominate each data packet making the effective data rate at layer 7 at least an order of magnitude less than the actual bit rate at the data link layer.

18.4.2 Connectionless transmission

The ISO OSI model can accommodate both connection and connectionless transmission modes. In the former an association between two or more peer entities, termed a connection, which has a clearly defined lifetime is established for data transfer purposes. This mechanism is the logical equivalent to a (circuit-switched) PSTN telephone call, and is employed in the virtual circuit strategy of X.25 packet-switched networks which operate at up to 64 kbit/s.

In connectionless-mode transmission data transfer can be achieved by a single access to a service, without the requirement for establishment and release phases. Here each self-contained data unit can be routed independently. This mode is particularly appropriate where interaction between pairs of entities is intermittent and infrequent, as in electronic mail or when bursty, variable bit rate, traffic occurs.

18.4.3 Physical layer protocol

For many years the most common, physical layer, connection standard has been RS232C, which defines the signal functions and their electrical characteristics in the two (forward and reverse) channel directions. RS232C is widely used for interconnecting terminals, PCs, printers, etc., and uses a minimum of three wires for the two channel connection. It can accommodate data rates of a little over 1 kbit/s on paths of up to 20 m. For longer distances (up to 1 km) and higher data rates, balanced transmission systems such as RS423A (10 kbit/s) and RS422A (1 Mbit/s) have been developed which reduce the effects of noise pickup on cables.

18.4.4 Synchronisation and line coding

A key requirement of the protocol processor is that it must be able to handle clock synchronisation, line encoding/decoding and frame synchronisation. A special synchronisation problem in LANs and MANs is that of the clock oscillators in the network's terminal equipment and nodes. For synchronised clock operation all

transmissions are synchronised with a common master station clock. For plesiochronous operation (section 19.3) each individual node receives data with a clock signal locked to the clock of the preceding node (or terminal). It then transmits data with its own local clock signal. Due to clock oscillator tolerance, this implies that the number of transmitted bits can differ from the number of information bits, requiring justification.

Line coding usually introduces redundancy into the data stream (see Chapter 6). This redundancy can be utilised for reliable clock recovery and for the coding of special control symbols. Long streams of consecutive identical bits are not desirable if this means that timing information cannot be regenerated easily from the incoming signal. Line codes can be divided into three classes, namely scrambled codes, bit insertion codes, and block codes. The function of a scrambler, in this context, is to generate transitions in the line-encoded data stream when the original data stream contains long sequences of identical bits, as in HDB3, section 6.4.5.

Examples of bit insertion codes are the 5B6B and 8B1C line codes. In the 5B6B-PMSI (periodic mark space insertion) scheme, the encoder alternately inserts a mark (one) and a space (zero) for every five information bits. In the 8B1C (8 binary with 1 complement insertion) scheme, every eight bits are preceded by one extra bit, which is the complement of the first of the eight bits. Block codes allow unique words to be transmitted for synchronisation purposes.

18.5 Medium access control

High-speed channel access schemes are divided into four main classes: random access, demand assignment, fixed assignment, and adaptive assignment protocols [Skov]. For each class, the protocols are further subdivided according to network topology.

18.5.1 Random access and demand assignment protocols

Random access is typified by the ALOHA packet switched systems which simply transmit whenever a message is ready to send and then waits to see if this transmission collides with other data on the system. This is very inefficient giving a maximum channel utilisation (or normalised throughput) of 18% [Kleinrock]. Slotted ALOHA, in which data is constrained to time slots, avoids partial packet overlap and therefore achieves a maximum utilisation of double this.

The best known access scheme for bus systems, because of its low installation cost, is carrier sense multiple access with collision detection (CSMA/CD). This scheme allows nodes to contend for use of the network and, in this sense, is similar to ALOHA. In CSMA/CD, however, any node ready to transmit first listens, sensing the carrier, to check whether another node is transmitting an information frame. If another transmission is already in progress, the node defers operation until the end of the current transmission. Once the network is free, the node transmits its addressed message. However, due to the non-zero propagation delay, two or more nodes can attempt to transmit simultaneously causing contention, which results in a collision. Given this situation, the transmission

attempt is aborted and the node waits a random period before retransmission to avoid possible step-lock. This is a more sophisticated access scheme than ALOHA and can realise a channel utilisation of 75%. At this utilisation efficiency, however, collisions introduce unpredictable network delay or latency.

With demand assignment access protocols, message transmissions are governed by serving, or allocating access to, the attached stations in a predetermined (typically cyclic) order. A representative token ring protocol (see section 18.2.4) for packet switched multimode optical fibre systems is the 125 Mbit/s fibre distributed data interface (FDDI). FDDI networks can employ ring lengths of 100 km with 2 km spacings between repeaters. The active optical repeaters receive light from the incoming fibre and regenerate data pulses which are coupled into the outgoing fibre. FDDI (see section 18.7.4) has been developed primarily as a dual broadband backbone ring with a high data rate for image transmission applications. Current developments in FDDI II are aimed at circuit switching for voice and video multimedia transmission.

EXAMPLE 18.1 – Token passing

A token passing ring operates at 2 Mbit/s with 10 stations, each with a latency of 2 bits, and uses a 4-bit token. If the cable delay round the ring is 10 μ s what is the maximum waiting time for access?

The total ring latency is $10 + (10 \times 2)/2 = 20 \mu$ s. Maximum waiting time is given by the total ring latency plus the token processing time which is $20 + 4/2 = 22 \mu$ s.

A variation on the conventional token ring is to partition time into slots and let these propagate round the ring. Access to a slot is possible, as it passes, provided it is not already filled with data. Such *slotted rings* can be divided into two groups depending on which station empties a full slot, the source station or the destination station. The fibre optic 600 Mbit/s Cambridge fast ring, section 18.2.4, employs source release.

Unidirectional buses integrate traffic with different priorities by means of rounds. Access to the bus typically follows one of three access schemes. When attempt-and-defer access is employed, a station wishing to transmit waits until the media is idle. It then begins its transmission and continues to listen to the media. If it detects a transmission from any upstream station, it aborts its transmission. The other schemes use polled or reservation access.

18.5.2 Fixed assignment protocols

In fixed assignment protocols the total network resource is divided among the participating stations in time, frequency, or code domain, in a fixed way. Thus, a station always occupies a part of the channel capacity, whether or not it has data to transmit. The protocols are TDMA, Figure 5.2, FDMA, Figure 5.12, and contention free CDMA, see section 15.5. Most of the FDMA and CDMA experimental ring and star networks use

optical signalling. CDMA permits uncoordinated accessing but may not offer the capacity of FDMA and TDMA, unless power control is adopted to avoid the near-far problem (see section 15.5.6).

18.5.3 Adaptive assignment protocols

At low loads, a device can usually transmit successfully as soon as it senses that the channel is idle. As the load rises, however, packet collisions may occur, thus destroying data. In such cases, adaptive protocols may switch to a more restricted, conflict-free, mode of operation such as token passing, attempt-and-defer, or TDMA access. An example of a high-speed network based on adaptive assignment access is the US 100 Mbit/s fibre optic HYPERchannel-100 network. This is based on a bus topology, and employs an access protocol that starts in CSMA/CD mode and switches to TDMA mode when collisions become too frequent.

18.6 International standards for data transmissions

18.6.1 X.25

This is the PSS standard which effectively replaces the telephone network, using the V-series recommendations (see section 11.6), with a digital system having superior error performance and fast switching. The X.25 recommendation defines the interface between terminal equipments and the public data network for packet-switched communication. A set of associated standards, X.3, X.28, X.29, have been developed to enable simple terminals to access an X.25 network. X.25 is actually a layered network access (interface) protocol that exhibits many of the properties of network architectures. The functionality of the X.25 specification corresponds entirely to the lower three layers in the ISO OSI model, Figure 18.12. In X.25, error checking is conducted at each node in the network. In the new frame relay systems this is only performed at the terminal stations.

X.25 PSS is now available within the UK as a core network for data communications, electronic mail, etc. One use of the network is for credit card verification and connections are available via telephone lines or radio access at 8 kbit/s [Davie and Smith]. Radio coverage in 1991 extended to 75% of the UK population for this data service.

18.6.2 IEEE 802

The IEEE 802.n specifications also map to the bottom three layers of the ISO OSI reference model. The IEEE split the data link layer into sub-layers: logical link control and medium-access control, which are used for bridging between networks. The 802.3 to 802.6 standards describe physical connections and define how access to the physical medium is coordinated for each LAN type. They therefore correspond to layer 1, and a sub-layer of layer 2, in the ISO OSI model.

- 802.2: Defines a logical link control layer.
- 802.3: Defines a CSMA/CD protocol, which is the basis of Ethernet, as implemented on coaxial, and twisted pair, cables.
- 802.4: Defines a token-passing bus protocol.
- 802.5: Defines a token-ring protocol (FDDI).
- 802.6: Is a broadband MAN standard (45 Mbit/s) for voice, data and video.
- 802.7: Specifies a broadband FDMA LAN (with 400 MHz of bandwidth).

These IEEE standards are now internationally accepted as ISO equivalent. 802.4 may eventually be replaced by FDDI-II.

18.7 Network examples

18.7.1 Manufacturers application protocol (MAP)

The manufacturers application protocol is implemented on a 10 Mbit/s broadband multidrop bus LAN using an 802.4 token passing bus channel employing RF carrier modulation. By operating on two separate carriers at frequencies between 59.74 and 264 MHz, simultaneous (FDM) data transmission and reception is accomplished using QAM signalling (Chapter 11). MAP is designed to interconnect plant (such as robots) in a manufacturing environment. Another commercial development is the fieldbus for interconnection of measuring instruments [Jordan]. In one network the bit rate is 1 Mbit/s with a maximum access time of 5 ms for a 32-node system. There are various other similar network designs, many of which share the IEEE 488 interface standard for digitising, encoding and transmitting signal samples from remote locations.

18.7.2 Admiral

The Alvey Admiral multimedia prototype network (Figure 18.14), developed in the mid 1980s, consists of baseband CSMA/CD Ethernet LANs at each of the five project sites, interconnected by a high speed network. This early example of a high speed network is configured as a star, with 2 Mbit/s primary rate access circuits from each user site to a central switch located at the star hub. At the centre of the network is a non-blocking switch providing configurable interconnection of any number of consecutive 64 kbit/s time slots within the 2 Mbit/s bearer to provide point-to-point links from site to site as required. User sites are able to alter the configuration of the network by sending commands to the switch controller, via the public X.25 network. This network was the first practical combination of fast local Cambridge rings and Ethernets with primary rate ISDN interconnections, as described in the following chapter.

18.7.3 Military LAN systems

The US MIL-STD-1553B and its UK equivalent DEF STAN 00-18 or STANAG 3838 applies to military ship, submarine and aircraft LANs. These 1970s systems used

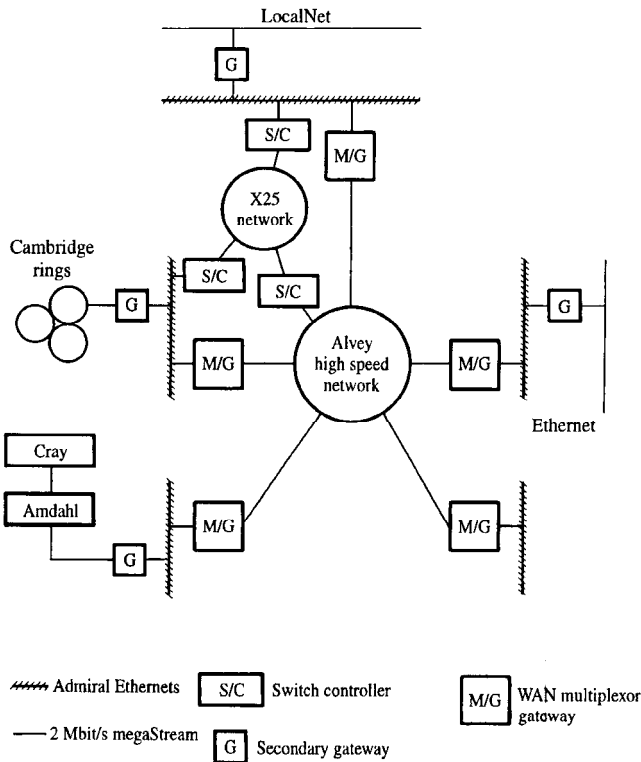


Figure 18.14 *The Admiral high-speed network.*

screened twisted pair cable to achieve 1 Mbit/s transmission rates with up to 31 remote terminals. Further US work has achieved high speed (20 to 40 Mbit/s) fibre optic networks while, in the UK, DEF STAN 00-19 is a 300 m multi-drop bus topology on a screened twin coaxial cable which signals at 3 Mbit/s. The bus for the European fighter aircraft, STANAG 3910, is a dual redundant 20 Mbit/s fibre optic implementation. It defines low speed 1 Mbit/s dual redundant wired channels plus the high speed 20 Mbit/s fibre optic channels. These specialised systems are not generally fully ISO compatible.

In contrast to civilian LANs, military ones require priority accessing schemes with short access delays for threat messages and must also be secure and free from transmission errors. These constraints inevitably result in specialised networks being developed for military applications.

18.7.4 Fibre distributed data interface (FDDI)

FDDI is a backbone broadband ring to which other, slower speed, tree networks and peripherals can be connected, Figure 18.15. (FDDI was conceived as a fast or broadband service to handle multimedia data transfer for applications such as desktop conferencing.)

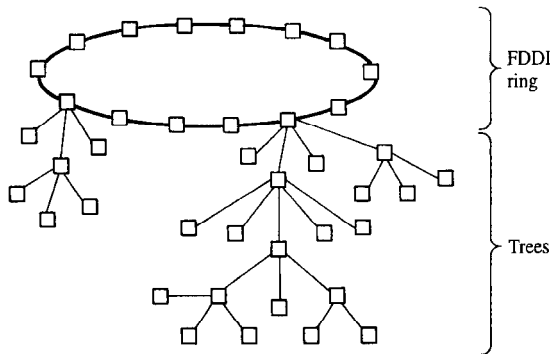


Figure 18.15 Network comprising FDDI high speed ring with tree connections.

The overall structure then looks like a ring-of-trees. FDDI operates at 100 Mbit/s as a plug-in multimode fibre ring (section 19.5) with 4B5B coding (which is a variation on the techniques described in section 6.4.7) implying a 125 MHz clock rate for this bit insertion code. Link P_b is 2.5×10^{-10} and packet error probability is 10^{-9} . On the maximum ring length of 200 km, ring transit time is 2.7 ms, corresponding to 60 full length packets. Packet latency for access to a network at 45 Mbit/s load is typically 50 to 200 μ s. Currently there is interest in copper distributed data interface (CDDI) using twisted pair cables, but this interest is more intense in North America than Europe. The FDDI structure of Figure 18.15 is not dissimilar to the future SDH inner core proposals employing ring networks (see section 19.4.1).

18.7.5 Wireless networks

There is much current interest in developing wireless systems to obviate the need for Ethernet wired connections between terminals and printers which are located in close proximity to each other. The US NCR WaveLAN is such a system which typically caters for 50 to 300 m link connections. In the indoor environment, if equalisation is not employed to combat multipath responses, then the data rate is typically limited to several hundreds of kbit/s. In WaveLAN systems 2 Mbit/s data is spread by a wideband (spread spectrum) modulator into an 11 MHz bandwidth channel. This wideband transmission permits the multipath signals to be separately resolved and their presence compensated for by equalisation in the receiver. Another system, HYPERLAN, operates using a 5.2 GHz carrier frequency with a 20 Mbit/s BPSK transmission rate [Halls].

EXAMPLE 18.2

A wireless network is to be designed for interfacing several portable, battery powered, laptop computers dispersed around an office environment using the HYPERLAN standard. Due to obstructions in the office path loss follows an inverse cube law with distance (rather than the free space inverse square law of Chapter 12). The portable computer power consumption is 15 W and

the wireless network should not *significantly* degrade the battery operating life. Estimate, using the link budget analysis of Chapter 12, the maximum operating range you might expect to achieve. Assume that the receiver noise figure is 10 dB, the (BPSK) signal requires a receiver CNR of 15 dB, a fade margin of 6 dB is necessary, the total implementation loss is 2 dB and the transmitter efficiency is 40%.

If the transmitter uses 10 to 15% of the battery power then the power available for the radio modem is 1.5 to 2.2 W. At 40% efficiency this gives approximately 0.75 W or 29 dBm of transmitted power.

The thermal noise floor in a 25 MHz bandwidth, from equation (12.8), is -100 dBm. The received carrier level must be larger than this by 10 dB (noise figure), 2 dB (implementation loss), 15 dB (receiver CNR requirement) plus 6 dB (fade margin). Thus, adding a total of 33 dB, the required received carrier level is $C = -67$ dBm.

The maximum tolerable path loss is thus $+29 + 67 = 96$ dB $= 4.0 \times 10^9$. FSPL is defined in Chapter 12. Using an R^{-3} law, equation (12.71) becomes:

$$\text{FSPL} = \left(\frac{4\pi}{\lambda} \right)^2 R^3$$

For isotropic antennas $G_T = G_R = 0$ dB $\equiv 1$. Thus for an operating frequency f and a free space propagation velocity c , the transmission loss, P_T/C , equals the FSPL, i.e.:

$$\frac{P_T}{C} = \text{FSPL} = \left(\frac{4\pi f}{c} \right)^2 R^3$$

Substituting numerical values and solving to find R :

$$4.0 \times 10^9 = \left(\frac{4\pi \times 5.2 \times 10^9}{300 \times 10^6} \right)^2 R^3 = \frac{4.74}{10^{-4}} R^3$$

$$R^3 = \frac{4.00}{4.74} 10^5 \text{ and } R = 44 \text{ m}$$

This range is typical for an office environment.

18.7.6 Internet

The Internet started life over 25 years ago as the ARPANET, section 18.1, which grew, initially, to link many university and industry laboratories in the US defence research community. It then became linked to Europe and gradually spread beyond the defence community, particularly as people realised that electronic mail could assist groups in many different organisations and countries to communicate effectively. The Internet is a communications medium, and a common set of protocols, which have been unified to form a coherent network.

Two separate developments ensured its rapid and widespread application. Firstly, it was demonstrated how a word in one document, located in one computer connected to the Internet, could be linked electronically to a previously unrelated document (a photograph, for example) stored on another computer, often in a different country. Many millions of

these *hypertext* links have now been put in place to better organise, and access, a wide range of different kinds of information. This has resulted in the world wide web (WWW) which uses a global web of linkages between an already huge, but ever growing, collection of information items and databases. Secondly, individuals started sharing information, such as pictures, on the Internet. For example, selecting the key word 'Hubble' would readily access not just data about the space telescope, but also the latest colour images originating directly from those computers controlling the telescope and analysing the data it generates. Thus, many individuals first saw the Hubble images of the cometary impact on Jupiter via the Internet.

The Internet is a network of networks, hence the name – *inter-network* network, and statistics about it are legion. In early 1995 it comprised around 50,000 networks, linking more than 2 million computers and perhaps 10 to 15 million users in many countries around the world. (It is not accurately known what the numbers are, because no single individual owns or controls the Internet.) It is self-regulating, capable of a high degree of rapid evolution and growth, and has been operated up to now by loose federations of individuals and organisations. What is really startling is the 20% per month growth of traffic on the Internet.

At its current rate of expansion, everyone on the planet would be connected to the Internet by 2003. A factor which is contributing to the growth of traffic is that commercial use of the Internet is now beginning to become important as the operation and maintenance of the underlying backbone networks in the US moves into the private sector. In 1994 there were over 21,000 commercial 'domains' registered on the Internet through which companies offer facilities to browse electronic catalogues and order goods and services. These commercial developments will change the fundamental character of the Internet. The Internet will evolve as this new technology matures and is used to provide services for home shopping, video entertainment, electronic banking, etc.

18.8 Summary

LANs, MANs and WANs refer to communications networks typically spanning individual buildings, individual towns, and individual countries, respectively. Such networks may be circuit switched, message switched or packet switched. Two forms of packet switching can be distinguished, i.e. virtual circuit and datagram switching – the former requiring all packets in a given message to traverse the same network route and the latter allowing packets to traverse independent routes. Historically the trend in network operation is from circuit switching (typified by the traditional PSTN), through message switching and virtual circuit switching, to datagram switching.

Network topologies include point-to-point, multidrop, star, ring, mesh and bus systems. Transmission media include twisted wire pairs, coaxial cable and optical fibres. Microwave and infrared links are also used to provide wireless connections between network terminals and nodes.

Bridges are used to interconnect networks using the same protocols (e.g. two similar LANs). Gateways are devices used to interconnect networks using different protocols

(e.g. a LAN and a WAN). Switches with self-routing properties can be employed at network nodes to improve switching speed over switches which require centralised control. Packet collisions at switch inputs can be avoided using an input sorting network and collisions at switch outputs avoided using a trap network.

The ISO OSI model for network protocol architectures has seven layers. The lowest three layers (physical, data link and network) specify the operation of the communications sub-net. The upper four layers are concerned with terminal equipment/network compatibility, initiation and control of a communication session, data formatting for correct presentation and the particular application being run by the user.

Medium access control (MAC) is one function of the data link layer in the OSI model. MAC protocols govern the allocation of physical medium resources (time, bandwidth, orthogonal codes) between network terminal equipments. These resources can be allocated on a fixed, demand or random assignment basis. Fixed assignment protocols are efficient if data terminal equipments (DTEs) have a heavy, and relatively constant, traffic load. Random access protocols are more efficient if traffic loads are highly variable and uncorrelated between terminals. Random access protocols suffer, however, from potential packet collisions if two or more DTEs attempt to access the medium simultaneously. Such contention can be resolved using CSMA/CD protocols. Fixed assignment systems may be adaptive in that the proportions of medium resource allocated to different terminals may track long term variations in terminal traffic loads. Systems may also be adaptive in the sense that an essentially fixed assignment protocol may be substituted for a (normally) random access protocol if collision detection occurs too frequently. Demand assignment systems allow terminals to commandeer medium resources as and when they are required. They may operate using centralised control, in which terminals are polled to ascertain their need for resources, or distributed control, in which token passing is employed. Bus systems typically use CSMA/CD protocols whilst ring systems typically use token passing.

X.25 is the ITU-T standard defining the interface between DTEs and data communication equipment (DCEs) for packet switched networks. The DCE is the interface with a node of the data network and may be located at the same site as the network node or be remote from it (as in the case of a modem used to connect a computer to the packet switched public data network via an analogue local loop of the PSTN). Other X-series standards specify the protocols for connecting low speed character mode terminals to packet networks using packet assemblers and disassemblers (PADs).

FDDI is a 100 Mbit/s, optical fibre, backbone ring network which supports lower speed tree networks at its nodes. Its maximum circumference is 200 km. Wireless networks, using radio transmission between nodes, are susceptible to frequency selective fading due to multipath propagation. Spread spectrum techniques can be used to mitigate the resulting distortion, allowing transmission at data rates many times that which the channel would ordinarily support.

The Internet is, at present, the ultimate WAN in that it gives, potentially, global coverage. In addition to the conventional data communication uses of a WAN, hypertext connections between different documents held on computers connected to the Internet result in the unparalleled information resource called the World Wide Web.